

# 3M™ Display M2256PW User Guide

Read and understand all safety information  
contained in this document before using this product.



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## CHAPTER 1

# Introduction

### Overview

Congratulations on the purchase of your 3M™ Touch Systems M2256PW Multi-Touch display. This guide describes how to set up your M2256PW Display.

The M2256PW Multi-touch Display is a 22” LCD with 16:10 aspect ratio with an attached desktop stand. 3M Multi-touch Technology, based on 3M Projected Capacitive touch technology and electronics, offers fast, accurate and simultaneous 20-finger touch functionality for next-generation, multitouch applications.

This display provides true multi-touch functionality supporting up to 20 independent touches as well as traditional pinch, expand and rotate features. Each touch is independently recognized thereby supporting true multi-touch and multi-user input.

The M2256PW Display uses projected capacitive technology with an all glass front surface and provides multi-touch functionality in a highly durable form factor. The fast response rate enables the creation of multitouch applications and supports real time rendering of maps and other speed sensitive applications.

### Important Safety Information

Read and understand all safety information before using this product. Follow all instructions marked on the product and described in this document. Pay close attention to the following installation warnings and safety precautions.

<b>Intended Use</b>
The 3M Touch Systems M2256PW Display was designed for touch input and tested to replace an existing display. These displays are intended for indoor use only and are not designed for use in hazardous locations.

### Explanation of Signal Word Consequences

**⚠ DANGER:** Indicates a potentially hazardous situation, which, if not avoided, will result in death or serious injury and/or property damage.

**⚠ WARNING:** Indicates a potentially hazardous situation, which, if not avoided, could result in death or serious injury and/or property damage.

**⚠ CAUTION:** Indicates a potentially hazardous situation, which, if not avoided, may result in minor or moderate injury and/or property damage.

**CAUTION:** Indicates a potentially hazardous situation, which, if not avoided, may result in property damage.

### ⚠ DANGER

**To avoid the risk of fire and/or explosion which will result in serious injury or death:**

- Do not install or use this product in a hazardous location.

### ⚠ WARNING

**To avoid the risk of fire which could result in serious injury or death:**

- Do not remove the cover or back of the display.

**To avoid the risk of electric shock which could result in serious injury or death:**

- Plug power cord into appropriate grounded power source.
- Do not use a damaged power supply.
- Do not use a power cord that is frayed or otherwise damaged.

### ⚠ CAUTION

**To avoid the risk of electric shock which may result in minor or moderate injury:**

- Do not service the Flat Panel Display yourself. There are no user serviceable parts inside. Refer all servicing to qualified service personnel.
- The backlight inverter output is at high voltage.
- Do not use non-conforming replacement parts.
- Do not place wet or damp objects on the display.
- Do not expose the display to rain or other sources of water, steam, or moisture.
- Do not place foreign objects on the display or its cables.
- Do not remove the cover or back of the display.
- Ensure that connecting the unit to the power source will not overload the power source.

**To avoid the risk of glass breakage which may result in minor or moderate injury:**

- Handle the display with care to avoid breaking the touch sensor. The display contains glass parts. Dropping the display may cause the glass parts to break.
- Ensure mounting screws are tightened fully to prevent instability.
- Do not place foreign objects on the display.

**⚠ CAUTION**

**To avoid the potentially hazardous situations associated with the use of isopropyl alcohol which may result in minor or moderate injury or property damage:**

Follow all instructions and recommendations in the manufacturer's Material Safety Data Sheet and product label.

**To avoid possible environmental contamination which may result in minor or moderate injury:**

- The lamp(s) inside this product contain mercury (Hg) and must be recycled or disposed of in accordance with local, state, or federal laws. Check your individual state's requirements to see if specific recycling requirements exist for mercury-containing products or other electronic products. Refer to <http://www.nema.org/lamprecycle/> or call 3M Touch Systems 1-866-407-6666 for further information.
- Dispose of the flat panel display according to applicable governmental regulations.

## Important Notes

- When unplugging power supply cord, hold the plug, do not pull by the cord.
- Do not connect or disconnect this product during an electrical storm.
- Install the display in a well-ventilated area. Always maintain adequate ventilation to protect the display from overheating and to ensure reliable and continued operation.
- Do not expose this display to direct sunlight or heat. Passive heat may cause damage to the housing and other parts.
- An inherent characteristic of the PCT sensor is a fine grid pattern that may be visible under certain lighting conditions.
- Do not install this display in areas where extreme vibrations may be generated. For example, nearby manufacturing equipment may produce strong vibrations. The vibrations may cause the display to exhibit picture discoloration or poor video quality.
- To avoid ergonomic concerns:  
Do not install the display in a manner or location with awkward accessibility. Extended use may result in muscle, tendon, or fixed posture strains. It is recommended you take periodic breaks from continuous use.

## Maintaining Your Touch Display

To maintain your display and keep your display operating at peak performance:

- Keep your display and touch sensor clean.
- Adjust the display video controls.
- Do not install the display in a place where ventilation may be hindered. Always maintain adequate ventilation to protect the display from overheating and to promote reliable and continued operation.

## Touch Sensor Care and Cleaning

The touch sensor requires very little maintenance. 3M Touch Systems recommends that you periodically clean the glass touch sensor surface. Be sure to turn off your display before cleaning.

Typically, an isopropyl alcohol and water solution ratio of 50:50 is the best cleaning agent for your touch sensor. You can also use straight isopropyl alcohol.

### CAUTION

To avoid the potentially hazardous situations associated with the use of alcohol or other solvents which may result in minor or moderate injury or property damage:

- Follow all instructions and recommendations in the manufacturer's Material Safety Data Sheet and product label.
  - Be sure to follow solvent manufacturer's precautions and directions for use when using any solvents
  - It is important to avoid using any caustic chemicals on the touch sensor. Do not use any vinegar-based solutions.
- 
- Apply the cleaner with a soft, lint-free cloth. Avoid using gritty cloths.
  - Always dampen the cloth and then clean the sensor. Be sure to spray the cleaning liquid onto the cloth, not the sensor, so that drips do not seep inside the display or stain the bezel.

## 3M Touch Systems Support Services

3M Touch Systems, Inc. provides extensive support services through our website and technical support organization. Visit the 3M Touch Systems website at <http://www.3m.com/touch/>, where you can download MT 7 software and drivers, obtain regularly updated technical documentation on 3M Touch Systems products, and learn more about our company.

Whenever you contact Technical Support, please provide the following information:

- Touch display size, part number and serial number
- Current driver version
- Operating system used
- Information on additional peripherals

Technical Support is available Monday through Friday 8:30 a.m. to 5:30 p.m. with limited call back service after 5:30 p.m. until 8:00 p.m. US Eastern Standard Time – 9 a.m. to 5 p.m. throughout Europe.

You can contact 3M Touch Systems, Inc. Technical Support (US only -- Eastern Standard Time) by calling the hot line, sending email or a fax.

- Technical Support Hot Line: 978-659-9200
- Technical Support Fax: 978-659-9400
- Toll Free: 1-866-407-6666 (Option 3)
- Email: US-TS-techsupport@mmm.com

## Contact 3M Touch Systems

Contact information for all offices can be found on our website at:

<http://www.3m.com/touch/>

## CHAPTER 2

# Setting up Your M2256PW Display

This chapter describes how to set up your 3M Touch Systems M2256PW Display. You need to complete the following tasks:

- Unpack the components
- Connect the video, touch display cables, and power cables
- Power on the display and test your setup
- If you are not running Windows 7 (or Tablet PC), install MT7 software from the enclosed CD. Note that this will not make multitouch happen -- it is up to your application to enable multitouch.

## System Requirements

The M2256PW Display requires a personal computer (PC). The requirements for your PC are as follows:

- Your PC must have an available USB or RS-232 serial communication (COM) port. You connect the touch sensor cable to this port.
- Your PC must have a video card and video driver already installed for the display. If you need to install a video card or a video driver, refer to your computer documentation for instructions.

When choosing your workspace, select a sturdy, level surface. Also, make sure you can easily access the back of the touch display and the computer. Easy access helps ensure a smooth setup of the touch display.

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**Note:** Before setting up your M2256PW Display, refer to the “Important Safety Information” section at the beginning of this document.

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## Unpacking Your Touch Display

Carefully unpack the carton and inspect the contents. Your M2256PW Display includes the following cables and accessories:

- USB and RS-232 serial communication cables
- DVI and VGA video cables
- Audio cable
- US and European power cables
- Software CD and documentation

### Cables Included with Your M2256PW Display



**USB Cable**



**9-pin RS-232 serial cable**



**EU power cable**



**US power cable**



**VGA cable**



**DVI cable**



**Audio cable**

## Connecting the Touch Display

**⚠ CAUTION**

You are cautioned that any change or modification to the equipment not expressly approved by the party responsible for compliance could void your authority to operate such equipment.

To connect the M2256PW Display:

1. Turn off your computer. You should always turn off the computer before connecting or disconnecting a device.
2. Select either the DVI or VGA cable. Connect one end of the video cable to the video connector on the display. Connect the other end to the video card in your computer.
3. Connect one end of the touch sensor cable (either USB or serial) to the LCD. Connect the other end to an available port on your computer.
4. Plug the AC power cord into the display.
5. Connect the power cable to an appropriate power source.

## Testing the M2256PW Display

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**Note:** The M2256PW display has a power status light located on the front of the bezel.

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After connection, turn on the power switch located at the bottom of the front bezel.

Before testing your touch display, make sure all cables are connected properly. Be sure to tighten all cable screws.

To test that the display is working properly:

1. Turn on your computer.
2. Make sure the video image is displayed. If it is not, check the LED to ensure that the display is not in power save mode (orange).
3. Make sure the video image is centered within the screen area. Use the display controls to adjust the image, if necessary.

You can adjust the horizontal and vertical position, contrast, and brightness to better suit your video card and your personal preference.

## Arm Mounting Option

The unit has a 100 mm VESA mounting pattern on the back to allow for arm mount capability. Use M4 x 8 mm screws to secure the VESA mount stand. Follow the manufacturer's instructions included with the mounting device to properly attach your display.

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**Note:** Do not use longer screws as they could potentially damage electronics inside the display.

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## Video Card Requirements

Before you connect your touch display, make sure your computer has a video card installed that supports the native video resolution of 1680 x 1050 for the M2256PW display. If you need information on installing a video card or video driver, refer to the manual that came with your video card.

## Using the Standard Controls for the Video Card

In addition to the standard controls on the display, each video card has several controls that let you adjust the display settings. The software and driver for each video card is unique. In most cases, you adjust these settings by using a program or utility provided by the manufacturer of the video card.

For example, you can use the Windows Display Properties control panel to adjust the desktop area (resolution), color depth, and refresh rate. Whenever you change these settings, the image size, position, or shape may change. This behavior is normal. You can readjust the image using the display controls described in this chapter.

For more information on adjusting the desktop area/resolution, color depth, or refresh rate, refer to the user manual that came with your video card. If you change the resolution, it is a good idea to calibrate your touch screen.

## Supported Video Display Modes and Refresh Rates

Your video card should support one of the display modes specified in Table 1. If you select an unsupported video mode, the display may stop working or display unsatisfactory picture quality.

**Table 1. Applicable Display Mode and Refresh Rate**

Display Mode	Refresh Rate (Hz)
640 x 350	70
640 x 480	60, 70, 72, and 75
720 x 400	70
800 x 600	56, 60, 70, 72, and 75
1024 x 768	60, 70, and 75
1280 x 720	60 and 75
1280 x 1024	60 and 75
1360 x 768	60 and 75
1680 x 1050	60

## Configuring the Display Settings

After you connect your M2256PW Display and turn on your computer, you may need to configure one or more of these display settings. The ideal setting for the M2256PW display is as follows:

- Display mode (also called desktop area or video native resolution) 1680 x 1050
- Refresh rate (also called vertical scan rate or vertical sync) 60 Hz
- Color depth (also called color palette or number of colors) at least 16-bit (high color)

## Multimedia Features

The M2256PW Display comes with speakers built into the back of the display housing and includes audio cables. These cables can be connected underneath the display.



## Access to the Video Controls

This section provides guidelines for adjusting the video display and using the display controls to adjust the image to your liking. The controls for adjusting the video display are located on the bottom right of the M2256PW Display. These buttons let you display the on-screen menu and adjust the phase, image position, contrast, and brightness. Before you make any adjustments:

- Be sure to adjust the controls in your normal lighting conditions.
- Display a test image or pattern whenever you adjust the video.



**Menu/Select Down Up Auto/Exit Power LED**

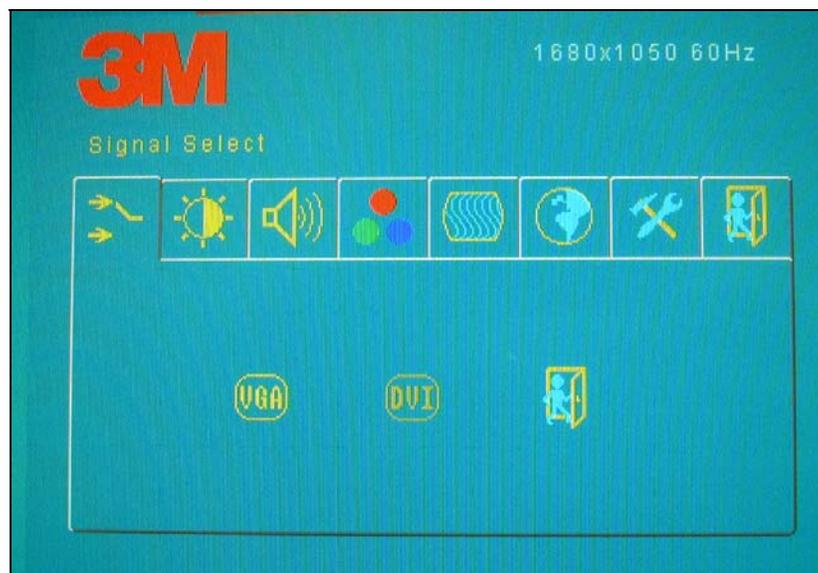
## Adjusting the M2256PW Video Display

Your M2256PW Display has four controls to adjust the video display.

- Menu – Shows or hides the on screen display menu.
- Select -- Highlights the current menu option or saves the current setting. Press ▲ or ▼ to change the value.
- ▲/Up -- Enables you to scroll forward through items on the menu -- increase the value of selected option or move to the next menu item.
- ▼/Down -- Enables you to scroll backwards through items on the menu -- decrease the value of selected option or move to the previous menu item.

If you do not press the Menu, Select, or ▲/up or ▼/down adjust buttons for up to 45 seconds, the display adjustment program times out and hides the menu options. You can press the Menu button at any time to display the options again.

Pressing Menu will pull up the On Screen Display (OSD) menu, as shown below.



OSD	Choices	Description
	  	<b>SIGNAL SELECT</b> Choices are <b>VGA, DVI, or Exit</b> Selects the applicable input source
	  	<b>VIDEO</b> Choices are <b>Brightness, Contrast, or Exit</b> <b>BRIGHTNESS</b> Selecting the Brightness option will allow you to adjust the brightness of the display. Adjust the brightness using the up and down buttons and press SELECT to confirm the new

OSD	Choices	Description
		setting. <b>CONTRAST</b> Selecting the Contrast option increases or decreases the strength (lightness or dimness) of the image. Adjust the contrast using the up and down buttons and press SELECT to confirm the new setting.
	 	<b>AUDIO</b> Adjust the volume of the speakers
	   	<b>COLOR</b> <b>Submenu Choices are User Defined Color, Preset Color Temperature, or Exit</b> <b>USER DEFINED COLOR</b> Adjust the Red, Green and Blue channels to your preference. <b>COLOR TEMPERATURE</b> Adjusts color temperature to PRESET 1 (6500 color temperature) or PRESET 2 (9300 color temperature).
	     	<b>IMAGE</b> <b>Choices are Auto Tune, Clock, Phase, H. Position, V. Position, or Exit</b> <b>AUTO TUNE</b> Performs automatic configuration of the Clock, Phase, Vertical and Horizontal positions. <b>CLOCK and PHASE</b> If the clock setting of your image is not fine-tuned, you may observe periodic vertical bars of video noise on your image. These bars of noise are usually adjusted out when an Auto Configuration is performed. If the bars of noise are still present, this setting can be adjusted manually. Adjust this setting so that either the vertical bars of noise are replaced by an even amount of noise across the whole screen, or the noise disappears completely. If you do an Auto Tune, the display will try to find the best Clock/Phase setting. If you are not satisfied with the auto adjustment, fine-tune the clock manually as described above. <b>H POSITION (Horizontal Position)</b> Moves image horizontally on screen either left or right. <b>V POSITION (Vertical position)</b> Moves images vertically on screen either up or down
		<b>LANGUAGE</b> Sets the language for the OSD -- the choices are English, French, German, Italian, and Chinese

OSD	Choices	Description
	      	<p><b>TOOLS</b>  <b>Choices are OSD Timing, OSD Horizontal, OSD Vertical</b></p> <p><b>OSD TIMING</b>            Adjust how long the menu remains on the screen. Submenu choices are: <b>Recall, Sharpness, or Exit</b></p> <p><b>OSD HORIZONTAL and VERTICAL</b>            Adjusts the position of the OSD on your screen</p> <p><b>RECALL</b>            Resets the control functions back to the original factory preset values. In order for the Recall function to work, the timing must fall under one of the factory preset timing modes.</p> <p><b>SHARPNESS</b>            Adjusts the video quality to be sharp or blurry (special for text mode).</p>
		<p><b>EXIT</b>            Exits the OSD menu.</p>

## CHAPTER 3

# Enabling Your M2256PW Display

### Windows™ 7 USB Compatibility

3M multi-touch technology works seamlessly with the Windows™ 7 operating system. The Multi-touch display supports USB HID for direct communication. The M2256PW display leverages all the multi-touch functionality that is native to Windows™ 7. Plug the display in to a system running Windows™ 7 and you'll quickly enter the world of true multi-touch functionality.

The M2256PW display is compatible with Windows 7 with no additional software. Refer to Microsoft's Windows 7 documentation for additional information.

### All Other Platforms

When using a Windows™ 7 serial connection or for Windows XP, Vista or Linux operating systems (either USB or serial), 3M provides MicroTouch MT 7 Software for multi-touch drivers. This guide includes information for writing your own drivers to interface with the 3M Multi-touch Technology.

For non-Windows 7 operating system users this document provides the communication protocol necessary to talk directly with the electronics. This enables software developers using other operating systems such as Microsoft Windows™ Vista or Linux® to write their own drivers and achieve the same multi-touch results.

### Multitouch Application Support

Remember not all applications are multitouch ready -- Multitouch behavior is a function of YOUR application. Check with your application vendor to determine if your software has multitouch capability.

## Installing 3M™ MicroTouch™ Software

Remember that Windows™ 7 does not require any additional software to enable multitouch functionality.

However, for Windows™ XP, Vista or Linux® operating systems, 3M™ MicroTouch™ Software enables your M2256PW display to work with your computer. 3M™ MicroTouch™ Software includes a control panel for setting your touch sensor preferences and a diagnostic utility. If you are experiencing problems with the touch sensor, you can use the diagnostic utilities provided to test the system.

For more information on installing this software and using the control panel, refer to the 3M™ MicroTouch™ Software User Guide on the accompanying CD or on the corporate website at [www.3m.com/touch](http://www.3m.com/touch).

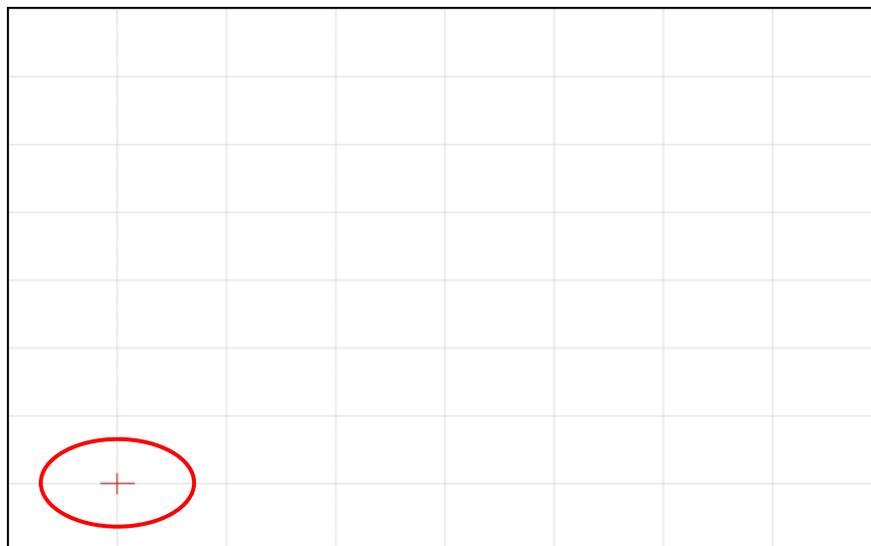
## Video Alignment

The M2256PW has been calibrated prior to shipment and the display as delivered should not require video alignment. You should be able to accurately touch icons on the sensor. If for some reason, you cannot do this, the touch sensor's active area may not be aligned to the underlying video.

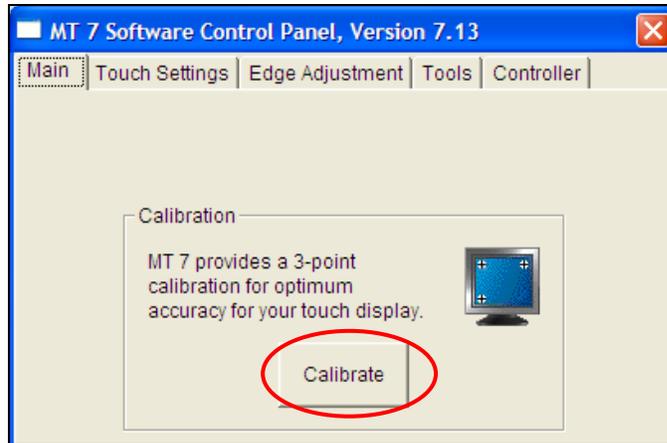
Regardless of the operating system, after you connect your touch display:

- If you are using Windows 7, you may calibrate by accessing the Software Diagnostic Utility (SDU) found on the enclosed CD.

Launch the SDU from the CD. Select the Tools menu and highlight Calibration. The screen below appears and you should touch the 2 targets as they appear. Press Escape to cancel Calibration.



- If you are using 3M™ MicroTouch™ MT 7 Software, launch the MT 7 Control Panel and follow the instructions on the Main tab. You'll be asked to touch 3 targets.



- If you are writing your own drivers, you should provide your own video alignment tool.

Use the Paint program (Start> Programs> Accessories> Paint) to determine if you have multitouch operation. Retest the accuracy after you perform a calibration.

## APPENDIX A

# 3M™ PX USB Controller Communications

This appendix is intended for software developers only and discusses the fundamentals of communicating with the PX controller. The firmware commands, which are usually issued by a driver or utility program on the host system, control the operation of the controller. This appendix lists the recommended firmware commands and describes how to use each of these commands.

## Overview of USB Firmware Communications

Developers may use this information when writing touch applications, developing custom drivers or touch configurations, or testing their touch systems. Developers can issue commands to initialize the controller, select operating modes, and execute diagnostic functions.

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**Note:** This document assumes you are familiar with USB standards and modes of communication with USB devices, as well as firmware commands and how to use them. Executing some commands may alter the performance of your sensor and render it inoperable. You should be aware of the results before executing any firmware commands.

---

To optimize the performance of the PX controller and simplify the development of custom drivers, 3M Touch Systems recommends you use the commands listed in this appendix for current development.

## Communication Basics

This section provides information on sending firmware commands to the controller and interpreting the responses that the controller returns. The default operation of the PX controller is USB Rev 2.0 full speed.

The USB command set is implemented by using vendor requests and vendor reports, i.e., vendor specific transactions. The controller issues some reports without prompting the computer. The computer can also send requests to the controller to change how it operates or receives information about the controller. The controller issues a synchronous report in response to some of these requests.

You need to know product ID (0502H) and the vendor ID (0596H) to write your own driver. These values are required for identifying the controller.

## Receiving Reports from the Controller

The controller sends a variety of reports to the computer. The first byte of each report is the Report ID that defines the structure and content of the report. The controller sends some reports as a direct response to a computer request (synchronous). The controller will also send some reports as the result of an external event, such as a touch (asynchronous).

## Command Set

The USB command set is implemented by using HID Get Feature and Set Feature commands. The various requests and reports are grouped together by report size under a common feature ID.

### HID Class Requests

The following table summarizes the available HID class requests.

**Table 1. HID Class Requests Summary**

HID Report	Command Name	bmRequest Type	bRequest	Feature Report ID	Report Subtype	Data Stage Bytes
Get Feature	GetStatus	0xA1 (D2H)	0x01	0x06	--	8
Set Feature	Calibrate	0x21 (H2D)	0x09	0x03	4	8
Set Feature	Reset	0x21 (H2D)	0x09	0x03	7	8
Set Feature	Restore Defaults	0x21 (H2D)	0x09	0x03	8	8
Get Feature	GetMaxCount	0xA1 (D2H)	0x01	0x12	--	2

## Set Feature - Calibration

This is a command to do a Calibrate Extended style calibration. The controller will auto-orient on this 2 point calibration.

**Table 2. Calibration Setup Stage**

Offset	Field	Size	Value	Description
0	bmRequestType	1	0x21	Class,H2D,Interface
1	bRequest	1	0x09	Set Report
2	wValue	2	0x0303	Msb 03 = Feature Lsb 03 = Feature Report ID
4	wIndex	2	0	Always 0
6	wLength	2	8	Always 8

**Table 3. Data Stage**

Offset	Field	Size	Value	Description
0	Report ID	1	0x03	Feature report ID
1	Report Subtype	1	0x04	Indicates a calibration request
2	bCalType	1	0x01	0x01 = Extended cal (CX)
3--7	Not used	5	0	Not used

The device stalls endpoint 0 if the command cannot be processed successfully. The request cannot be processed if an invalid calibration type is given in the wValue field. The request will also fail if the 2 calibration points do not fall within certain bounds established by the firmware. These bounds require that the 2 calibration points be in opposite quadrants of the sensor.

The host should issue a GetStatus request to determine the status of this request. The status report includes a command status byte which will be set as shown below.

**Table 4. Calibration Response**

Command Status Byte	Description
0	Calibration Failed
1	Controller is waiting for a touch in the lower left corner. Calibration software paints a target in the lower left corner.
2	Controller is waiting for a touch in the upper right corner. Calibration software paints a target in the upper right corner.
3	Calibration completed successfully.

The controller does not timeout waiting for touch. Use the soft reset command to abort the calibration.

### Determining Target Areas

The default calibration targets (points) are located 12.5% (1/8) inward from the corners of the video image. For example, suppose the resolution of your Windows-based display is 1680 x 1050. The Calibrate Extended command calculates the amount to move inward as follows:

- Amount to move inward in the X direction:  $1680 \times 1/8 = 210$
- Amount to move inward in the Y direction:  $1050 \times 1/8 = 131$

The Calibrate Extended command then positions the first calibration target inward from the lower left corner (0,1049) and the second calibration target inward from the upper right corner (1679,0). The following illustration shows how the calibration targets are calculated for a Windows-based system. Your operating system may be different.

The illustration below shows the coordinates of the calibration targets and display corners. The corners show the video coordinates in parentheses and the touch screen coordinates in brackets.



## Get Feature - GetStatus

This is a request to send information that indicates the status of the controller. Among the uses for this request are determining whether there were any power on check errors and determining whether the last request was completed successfully.

**Table 5. Controller Status Setup Stage**

Offset	Field	Size	Value	Description
0	bmRequestType	1	0xA1	Class,D2H,Interface
1	bRequest	1	0x01	Get Report
2	wValue	2	0x0306	msb=03=Feature lsb=06= Feature Report ID
4	wIndex	2	0	Always 0
6	wLength	2	8	Always 8

**Table 6. Controller Status Data Stage (controller response)**

Offset	Field	Size	Value	Description
0	Report ID	1	0x06	Feature Report ID
1	POC Status	1	0xXX	Power On Check Status
2	Cmd Status	1	0xXX	Status of last command
3	Touch Status	1	0	Not used
4	Async Reports	1	0xXX	0x00 = async touch output off 0x01 = async touch output on
5-7	Not used	3	0	Not used

POC Status – The status of the Power-on Checks. Various controller systems are checked at power-up. If any failures in these systems are detected, a POC flag is set. The POC status field reports the state of these flags.

**Table 7. Power On Check Bit Fields**

Bit Number	Description	Notes
0	Not used	
1	ROM_ERROR	Code area checksum error
2	PWM_Error	Touch screen not connected or potential problem
3	NOV_ERROR	Parameter blocks checksum error
4	HDW_ERROR	Problem with ADCs
5--7	Not used	

Cmd Status – The status for the last command request. This field is used to determine whether the last request was processed successfully. It is also used to track the progress of a multi-stage request, such as 2 point calibration. The Status Request does not affect the contents of this field, i.e., successful or unsuccessful processing of a previous status request does not cause the command status field to be updated.

**Table 8. Valid Command Status Field Entries**

Response	Description
0	Failure in command processing
1	Command being processed
2	Stage 1 processing complete (for multi-stage commands)
3	Command complete
4	Soft Reset Occurred
5	Hard Reset Occurred
6 -- 7	Not used

### Get Feature - GetMaxCount

This is a request to send information that indicates the maximum number of simultaneous touches supported by the controller.

**Table 9. Setup Stage**

Offset	Field	Size	Value	Description
0	bmRequestType	1	0xA1	Class,D2H,Interface
1	bRequest	1	0x01	Get Report
2	wValue	2	0x0312	msb=03=Feature lsb=12 Feature Report ID
4	wIndex	2	0	Always 0
6	wLength	2	2	Always 2

**Table 10. Data Stage (controller response)**

Offset	Field	Size	Value	Description
0	Report ID	1	0x12	Feature Report ID
1	Max Count	1	0x1E	Number of actual 30 fingers supported

**Note:** The number of actual contacts reported may exceed this number (possibly up to 60).

### Set Feature - Reset

This is a request to perform a controller reset. Soft resets are automatic after any block parameter changes.

**Table 11. Reset - Setup Stage**

Offset	Field	Size	Value	Description
0	bmRequestType	1	0x21	Class,H2D,Interface
1	bRequest	1	0x09	Set Report
2	wValue	2	0x0303	msb=03=Feature lsb=03= Feature Report ID
4	wIndex	2	0	Always 0
6	wLength	2	8	Always 8

**Table 12. Reset – Data Stage**

Offset	Field	Size	Value	Description
0	Report ID	1	0x03	Feature Report ID
1	Report Subtype	1	0x07	Indicates a reset request
2	bResetType	1	0x01	Soft Reset
			0x02	Hard Reset
3--7		5	0	Not used

A Hard Reset will cause the controller to reenumerate.

In the case of a Soft Reset, after sending the command, the controller will acknowledge (ACK) the transfer, but the command will not yet be completed. Before sending any other commands, the host should poll with GetStatus until the command status field returns “Soft Reset Occurred,” “Command Complete,” or “Fail”. Any timeout for this status polling should be 2 seconds minimum.

### Set Feature –Restore Defaults

This is a request to restore parameter defaults.

**Table 13. Restore Defaults -- Setup Stage**

Offset	Field	Size	Value	Description
0	bmRequestType	1	0x21	Class,H2D,Interface
1	bRequest	1	0x09	Set Report
2	wValue	2	0x0303	msb=03=Feature lsb=03= Feature Report ID
4	wIndex	2	0	Always 0
6	wLength	2	8	Always 8

**Table 14. Restore Defaults - Data Stage**

Offset	Field	Size	Value	Description
0	Report ID	1	0x03	Feature Report ID
1	Report Subtype	1	0x08	Restore Defaults
2-7		6	0	Not used

After sending this command, the controller will acknowledge (ACK) the transfer, but the command will not yet be completed. Before sending any other commands, the host should poll with GetStatus until the command status field returns “Command Complete” or “Fail”. Any timeout for this status polling should be 2 seconds minimum.

## Asynchronous Reports

### Coordinate Data – MultiTouch Digitizer mode Async Report 0x13

This is used to transfer the coordinate data to the host. This report, when activated, is sent to the host whenever new data is available/scheduled for transmission. It is an asynchronous report that is activated by default at power up. See SetAsyncReport for details on how to activate/deactivate an asynchronous report.

The report shown supports up to 6 simultaneous touches. Note that if more than 6 touches were to be supported, Report 0x13 would be sent as many times as necessary to accommodate the number of fingers touching. Only the first Report 0x13 will have a non-zero actual count. Each valid touch is marked with an ID number that remains the same from touchdown thru liftoff. The ID number can be any value from 0 to 255. Ignore all other data within a touch report structure with a status marked “not valid”.

The coordinate system is Upper Left origin.

**Table 15. Coordinate Data Report 0x13 --Data Stage**

Offset	Field	Size	Value	Description
0	Report ID	1	0x13	Report ID
1	Touch Report	10	See table 16	Touch Report Structure
11	Touch Report	10	See table 16	Touch Report Structure
21	Touch Report	10	See table 16	Touch Report Structure
31	Touch Report	10	See table 16	Touch Report Structure
41	Touch Report	10	See table 16	Touch Report Structure

Offset	Field	Size	Value	Description
51	Touch Report	10	See table 16	Touch Report Structure
61	Actual Count	1	1 to 60	Number of valid touch reports
62	Not used	1	0	
63	Not used	1	0	

**Table 16. Touch Report Structure**

Offset	Field	Size	Value	Description
0	Status	6	0xXX	0x00 Report not valid 0x04 Not touching 0x07 Touching
1	Touch ID	1	0-255	Touch thread ID number
2	X lsb	1	0xXX	X ( 0-7FFF)
3	X msb	1	0xXX	
4	Y lsb	1	0xXX	Y ( 0-7FFF)
5	Y msb	1	0xXX	
6	Width lsb	1	0xXX	Width ( 0-7FFF)
7	Width msb	1	0xXX	
8	Height lsb	1	0xXX	Height ( 0-7FFF)
9	Height msb	1	0xXX	

## APPENDIX B

# 3M™ PX Serial Controller Communications

This appendix is intended for software developers only and discusses the fundamentals of communicating with the 3M™ PX serial controller. The firmware commands, which are usually issued by a driver or utility program on the host system, control the operation of the controller; however developers can enter these commands directly. This appendix:

- Describes the controller default settings.
- Lists the recommended firmware commands for current development.
- Describes how to use each of these commands.
- References additional commands developers may need to use.

The description of each command includes the command syntax, the default value, how the command works, and the expected response from the controller.

## Overview of Firmware Commands

Developers may use these commands when writing touch applications, developing custom drivers or touch configurations, or testing their touch systems. Developers can issue commands to initialize the controller, select operating modes, and execute diagnostic functions.

---

**Note:** This document assumes you are familiar with standards and modes of communication with serial devices, as well as firmware commands and how to use them. Executing some commands may alter the performance of your sensor and render it inoperable. You should be aware of the results before executing any firmware commands.

---

To optimize the performance of the 3M™ PX controller and simplify the development of custom drivers, 3M Touch Systems recommends you use the commands listed in this appendix for current development.

## Controller Default Settings

### Communication Parameters

The operation of the PX serial controllers is N81 (no parity, 8 data bits, and 1 stop bits) at 115,200 baud (nonadjustable).

## Data Format

*Data format* refers to the type of packet the controller uses to send the X/Y touch coordinates to the host system. Format Tablet Multitouch is the default format for the 3M™ PX serial controller. In Format Tablet Multitouch, the controller sends 6 bytes per point and provides the most rapid response time to a touch.

Refer to the Format Tablet Multitouch command in the firmware reference section. Note that 3M MicroTouch Software automatically sets communications parameters to N81.

## Operating Mode

The *operating mode* specifies the conditions under which the controller sends the X/Y touch coordinates (input data packet) to the host system.

Mode Stream is the default operating mode for the PX serial controller. In Mode Stream, the controller sends a continuous stream of data packets when the sensor is touched. The controller sends the data as long as a touch continues on the sensor.

Because Mode Stream sends touch data continually, it is the most versatile mode, and it provides the best response time and overall feel.

3M Touch Systems recommends that the touch driver generate an interrupt as each packet in the data stream arrives. Because touchdown and liftoff events are specially coded, your software can generate mouse events that correspond to what the user is doing. This enables instant feedback and prevents data loss.

## Communicating with the Controller

This section provides information on sending firmware commands to the controller and interpreting the responses that the controller returns.

The commands listed in Table 17 are those that 3M Touch Systems currently uses for development. 3M Touch Systems recommends that you use only these commands for 3M™ PX serial controller development.

Commands to the controller are sent on the signal **Receive Data (RXD)** line as a serial data stream. For each command it receives, the controller sends a response to the host on the signal **Transmit Data (TXD)** line also as a serial data stream.

### Sending Commands to the Controller

When you send a command to the controller, you must use the correct command format. The general format of a command is as follows:

<Header>Command<Terminator>

---

**Note:** The following descriptions of header, command, and terminator, use 3M Touch Systems terminal emulator key sequences. You may need to enter the sequence in a different format, depending on your emulator.

---

The *header* is the first character in the command string and is the ASCII start-of-header control character SOH. The hexadecimal code for the ASCII SOH control character is 01. To start the command sequence, use the key combination Ctrl A (^A). If you are working with an IBM PC compatible system, the Ctrl A key combination immediately returns an ASCII ☺ character.

The *command*, which always follows the header, consists of ASCII uppercase letters and numbers only (printable characters).

The *terminator* is the last character of each command string and is an ASCII carriage return CR. An ASCII CR control character is 0D hexadecimal. To enter a carriage return, ending the command sequence, use Enter or the key combination Ctrl M (^M).

This appendix lists each command as a string of ASCII control characters and printable characters consisting of a header, the command, and a terminator as follows:

<SOH>*Command*<CR>

## Receiving Responses from the Controller

After executing a command, the controller returns a response or acknowledgment to the host system. Each controller response consists of a header, the command response, and a terminator in the following format:

<Header>Command Response<Terminator>

---

**Note:** The following descriptions of header, response, and terminator, use 3M Touch Systems terminal emulator key sequences. The format of controller responses varies depending on the terminal emulation mode you are using.

---

The *header* is the first character in the response string and is the ASCII start-of-header control character SOH. The hexadecimal code for the ASCII SOH control character is 01. If you are working with an IBM PC compatible system in terminal mode, the SOH control character returns a ☺ character to the sensor.

The *command response*, which always follows the header, is a range of ASCII characters depending on the type of command sent. Responses can be in many forms. For example, one standard response is **0** (ASCII character ‘zero’ or 30 hexadecimal). This response indicates a successful command completion for most commands, while it indicates a failed completion for other commands. Refer to the firmware reference section for a description of what the response indicates for *each* particular command.

Another standard response is **1** (ASCII character ‘one’ or 31 hexadecimal). In most cases, this response indicates the command failed. The controller received an invalid command that it could not execute.

Some possible reasons for a command failure include:

- The command was not formatted correctly.
- The system parameters were not set up to allow command execution.
- The controller does not support the command.

The *terminator* is the last character of each response string and is an ASCII carriage return CR. The hexadecimal code for the ASCII CR control character is 0D hexadecimal. The value returned in the response will be the ASCII control character for a carriage return, displayed on the screen as the cursor moving to the next line.

In this appendix, responses are shown as a string of ASCII characters consisting of a header, the response, and a terminator as follows:

```
<SOH>Response<CR>
```

## Controller Initialization

To initialize the PX serial controller for new development, 3M Touch Systems recommends that the host system issue a Reset command whenever the host system is powered on and is attempting to establish communication with the controller.

## Firmware Commands

Developers may use this information when writing touch applications, developing custom drivers or touch configurations, or testing their touch systems. Developers can use firmware commands to initialize the controller, select operating modes, specify data formats, and execute diagnostic functions.

---

**Caution:** This document assumes you are familiar with firmware commands and how to use them. Executing some commands may alter the performance of your touch system and render it inoperable. You should be aware of the results before executing any firmware commands.

---

To optimize the performance of the touch controller and simplify the development of custom drivers, 3M Touch Systems recommends you use the commands listed in Table 17 for current development. Using these commands ensures compatibility with all 3M™ controllers.

---

**Note:** When you enter commands in terminal mode, precede each command with <CTRL> A to enter the start of header.

---

**Table 17. Firmware Commands for PX Serial Controller Development**

Command	Code	Description
Calibrate	CX	Initiates an interactive 2-point calibration.
Get Copyright	Q101	Returns the copyright string.
Mode Down Up	MDU	Reports touchdowns and liftoffs only.
Mode Inactive	MI	Turns off touch reports.
Mode Stream	MS	Default mode. Streaming touch reports.
Name	NM	Returns a controller identifier string.
Null Command	Z	Returns an ACK. No effect.
Output Identity	OI	Returns Identity string: ADxxxx
Reset	R	Resets certain modes and gets a new baseline.
Restore Defaults	RD	Restores default settings.
Unit Type	UT	Returns the Status string: AD***ss.

## Calibrate

Syntax: <SOH>**CX**<CR>

Response: <SOH>**1**<CR> Valid point response.

A Valid Point Response ('1') signifies that a touch coordinate was detected and is in range of the expected screen target area. Two valid point responses indicate successful calibration.

<SOH>**0**<CR> Invalid point response

An Invalid Point Response ('0') is returned if the touch coordinate is out of range. If either calibration point is invalid, the touch coordinates are discarded and the calibration points remain unchanged from their previous values.

<SOH>**2**<CR> Invalid point response

An Invalid Point Response ('2') is returned if the user did not touch the target long enough to provide an accurate point.

Description: Initiates an interactive 2-point calibration.

During the calibration process, you define the active area of the touch sensor by mapping locations to an absolute X/Y coordinate system. You touch two *target areas* on the sensor. Touching the target areas sends the X/Y coordinates for those touch points to the controller. The controller calculates all other touch points based on these two points.

The Calibrate command sets the calibration targets (points) 12½ percent inward from the corner of the video image. Setting the targets inward makes the calibration process easier and more accurate.

It also establishes screen orientation.

### Calibrate Procedure

To use the CX command:

1. Enter the Calibrate (CX) command. The controller sends an initial acknowledgment of <SOH>0<CR>.
2. Touch the sensor at a lower left target, which is located 12.5% (1/8) in from the corner of the video image. The controller returns an acknowledgment of <SOH>1<CR>. This is a positive response. If you receive a negative response <SOH>0<CR>, you can cancel the calibration by issuing a Reset command and then start over again.
3. Touch the sensor at an upper right target, which is located 12.5% (1/8) in from the corner of the video image. The controller returns an acknowledgment of <SOH>1<CR>. This is a positive response. If you receive a negative response, you must start over again.

Touching the two valid calibration points results in a successful calibration. If either calibration point is invalid, the calibration fails. The PX controller restores the previous calibration values. If Calibrate fails, repeat the CX process.

## Guidelines for Calibrate Command

Here are several guidelines for using the Calibrate commands:

- The controller uses the data immediately before liftoff to register a calibration touch. Therefore, you can touch the coordinate target, hold for a few seconds, and then lift off. Instructing users to touch this way results in a more accurate calibration.
- The controller stores the data in non-volatile memory (NOVRAM). Therefore, you do not have to calibrate the sensor each time you power on the system. You should, however, recalibrate the touch sensor any time the video display changes size or resolution.
- You can cancel calibration at any time during this sequence by issuing a Reset command.

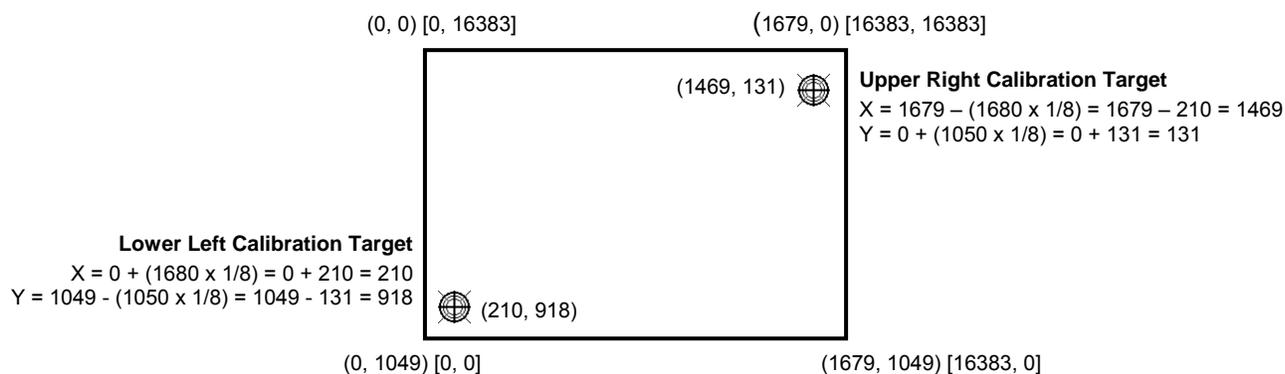
### Determining Target Areas

The default calibration targets (points) are located 12.5% (1/8) inward from the corners of the video image. For example, the resolution of your Windows-based display is 1680 x 1050. The Calibrate Extended command calculates the amount to move inward as follows:

- Amount to move inward in the X direction:  $1680 \times 1/8 = 210$
- Amount to move inward in the Y direction:  $1050 \times 1/8 = 131$

The Calibrate Extended command then positions the first calibration target inward from the lower left corner (0,1049) and the second calibration target inward from the upper right corner (1679,0). The following illustration shows how the calibration targets are calculated for a Windows-based system. Your operating system may be different.

The illustration below shows the coordinates of the calibration targets and display corners. The corners show the video coordinates in parentheses and the touch screen coordinates in brackets. Note that the touch screen coordinates for the serial interface have their origin in the lower-left corner.



## Get Copyright

Syntax: <SOH>**Q101**<CR>

Response: <SOH>**Copyright © 2010 3M. All rights reserved.**<CR>

Description: This command is used to get copyright information.

## Mode Down Up

Syntax: <SOH>**MDU**<CR>

Response: <SOH>**0**<CR> Positive response.

Description: Limits touch reports to touchdown and liftoff events only.

## Mode Inactive

Syntax: <SOH>**MI**<CR>

Response: <SOH>**0**<CR> Positive response.

Description: Turns off touch reports.

## Mode Stream

Syntax: <SOH>**MS**<CR>

Response: <SOH>**0**<CR> Positive response.

The controller will respond with acknowledge (ACK) for compatibility. This format is the only format supported by this controller.

Description: This is the default mode of operation at power up. Touch reports include touchdown and liftoff events as well as continuing touches.

## Name Command

Syntax: <SOH>**NM**<CR>

Response: <SOH>**0**<CR> Positive response.

Description: Returns a name string

## Null Command

Syntax: <SOH>**Z**<CR>

Response: <SOH>**0**<CR> Positive response.

Description: Queries the controller and waits for a response.

Use Z to determine that you are communicating with the controller or to make sure that a utility is communicating with the controller. Using this command does not affect the controller's current operating parameters.

## Output Identity

Syntax: <SOH>**OI**<CR>

Response: <SOH>AD**Xxxx**<CR>

where:

*AD* = Two ASCII characters that describe the type of 3M Touch Systems controller.

*Xxxx* = This is a unique identifier not necessarily the actual firmware revision number.

Description: Returns a 6-character identifier, which describes the controller type and the firmware version number. .

## Soft Reset

Syntax: <SOH>**R**<CR>

Response: <SOH>**0**<CR> Positive response.

Description: Initializes the hardware and the firmware, causes the controller to stop sending data, and recalculates the environmental conditions (for example, stray and offset values). The Reset command also cancels the Calibrate command and returns the controller to normal operation.

3M Touch Systems recommends that the host system issue a Reset command whenever the host system is powered on and is attempting to establish communication with the controller.

The amount of time needed to execute a Reset command is typically 500 milliseconds with a defined maximum of 2000 milliseconds. Therefore, the application program should wait and be sure it receives the command response before issuing another command to the controller following the reset.

## Restore Defaults

Syntax: <SOH>**RD**<CR>

Response: <SOH>**0**<CR> Positive response.

Description: Returns to the factory default operating parameters. The Restore Defaults command copies the 3M Touch Systems factory default parameters from ROM to the non-volatile memory (NOVRAM) and then executes a Reset command.

The following table lists the factory defaults for the PX controller. The Restore Defaults command is useful in situations where inadvertent commands to the controller have rendered the sensor inoperative.

**Table 18 PX Factory Default Settings**

Operating Parameter	Default
Baud Rate	115,200
Serial Communication Settings	N, 8, 1

---

Data Format	Format Tablet Multitouch
Operating Mode	Mode Stream
Return to Factory Calibration	Yes

---

**Note:** After you issue a Restore Defaults command, you must recalibrate your sensor.

---

## Unit Type

<SOH>**UT**<CR>

Responds with an 8-character identity string. This string identifies the type of controller currently attached to the system, lists the features supported by the controller, and outputs the status of the controller hardware (a self-test code).

Returns an identification code up to 8 ASCII characters in the following format:

<SOH>*TtFffSs*<CR>

where:

*Tt* = Two ASCII characters that identify the controller type.

**AD** Indicates the PX series of controllers

*Ffff* = Four ASCII characters that indicate the features supported by the controller.

**\*\*\*\*** Indicates no additional features configured

*Ss* = Two ASCII characters that provide status information about the controller hardware. The two characters represent one byte. Each character is in the range 0 to 9 and A to F.

Table 2 defines the meaning of each bit in the status byte. Each bit can be set to 1 or 0, where **1** = an error and **0** = no error. So a response of:

**00** = No diagnostic errors (normal response)

The PX running with no errors returns the following string:

<SOH> **AD\*\*\*\*00** <CR>

The format includes two bitmapped ASCII hex status bytes. A “00” indicates no errors.

**Table 19 Bit Meanings in Status Byte**

Bit	Description	Notes
0	Not used	
1	ROM ERROR	Code area checksum error
2	PWM Error	Touch screen not connected or potential problem.
3	NOV ERROR	Parameter Block1 checksum error
4	HDW ERROR	Problem with ADCs
5	Not used	
6	Not used	
7	Not used	

## Touch Data Format

The format is a six byte packet that includes one status byte, four bytes of binary X,Y position data and a touch ID. The X,Y coordinates are 14 bits, providing a range of 0 to 16,383. The data is sent in the following format:

**Table 20 Touch Data Format Settings**

Data Sequence	Bits							
	7	6	5	4	3	2	1	0
Status - Byte 1	1	P <sup>1</sup>	0	0	0	0	0	0
X - Byte 2	0	X6	X5	X4	X3	X2	X1	X0
X - Byte 3	0	X13	X12	X11	X10	X9	X8	X7
Y - Byte 4	0	Y6	Y5	Y4	Y3	Y2	Y1	Y0
Y - Byte 5	0	Y13	Y12	Y11	Y10	Y9	Y8	Y7
ID - Byte 6	0	N6	N5	N4	N3	N2	N1	N0

Note 1: P is the proximity bit. It is set to 1 when there is a touch, 0 for a liftoff.

The ID is associated with a touch stream from one finger. The ID, in the range of 0-127, is assigned on a rotating basis at touchdown. A finger touch stream consists of a touchdown, maybe some continuing touch points, ending with a liftoff. The ID is released on liftoff, and becomes available to be reassigned.

When multiple fingers are down, the packets from the touch streams are sent interleaved. There is no order imposed on the interleave.

## APPENDIX C

# Regulatory Information

### Regulatory Agency Approvals

Your product complies with the following regulatory standards:

- FCC-B
- CE
- UL60950/IEC60950/EN60950 certified in compliance with the CB test scheme
- RoHS/WEEE directives

This equipment has been tested and found to comply within limits for a Class B digital device, pursuant to Part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference in residential installations. This equipment generates, uses and can radiate radio frequency energy, and if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television equipment reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Move the equipment away from the receiver.
- Consult the dealer or an experienced radio/television technician for additional suggestions.

** CAUTION**

You are cautioned that any change or modification to the equipment not expressly approved by the party responsible for compliance could void your authority to operate such equipment.

This Class B digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.

Cet appareil numérique de la classe B respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada.

This device complies with Part 15 of the FCC rules: Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

## FCC Warning

To assure continued FCC compliance, the user must use grounded power supply cord and the provided shielded video interface cable with bonded ferrite cores. If a BNC cable is going to be used, use only a shielded BNC(5) cable. Also, any unauthorized changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate this device.

3M Touch Systems is not responsible for any radio or television interference caused by using other than recommended cables and connectors or by unauthorized changes or modifications to this equipment.

## CE Conformity for Europe

The device complies with the requirements of the ECC directive 2004/108/EC with regard to "Electromagnetic compatibility" and 2006/95/EC with regard to "Safety".